

A New Class of Sequential Circuits with Acyclic Test Generation Complexity

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Abstract—This paper introduces a new class of sequential circuits called acyclically testable sequential circuits which is wider than the class of acyclic sequential circuits but whose test generation complexity is equivalent to that of the acyclic sequential circuits. We also present a test generation procedure for acyclically testable sequential circuits and elaborate a design-for-test (DFT) method to augment an arbitrary sequential circuit into an acyclically testable sequential circuit. Since the class of acyclically testable sequential circuits is larger than the class of acyclic sequential circuits, the DFT method results in lower area overhead than the partial scan method and still achieves complete fault efficiency. Besides, we show through experiment that the proposed method contributes to lower test application time compared to partial scan method. Moreover, the proposed method allows at-speed testing while the partial scan method does not.

Index Terms—Acyclic test generation, design-for-test, sequential circuits, test generation complexity.

I. INTRODUCTION

Test generation even for combinational circuits, was shown to be NP-complete almost three decades ago [1]. However, empirical observations tell us that the test generation complexity of practically encountered combinational circuits seems to be polynomial [2]. Based on this observation, several classes of sequential circuits whose test generation complexity is equivalent to combinational test generation complexity have been introduced. These include balanced sequential circuits [3] and internally balanced sequential circuit [4]. In our previous work [5], [6], we introduced τ^k notation to express the test generation complexity of a given circuit class relatively to the combinational test generation complexity denoted as $\tau(n) = \Theta(n^r)$ where n is the size of the combinational circuit and r is some constant larger than 2. Using time expansion model (TEM) [7], we showed in [5], [6] that the class of acyclic sequential circuits is τ^2 -bounded, which means the test generation complexity of acyclic sequential circuits is bounded by the square of the combinational test generation complexity, i.e. $O(\tau^2(n))$. Therefore, we regard acyclic sequential circuits as easily testable. Thru function has been used in [9] to reduce test generation complexity but the target circuit is datapath only and test generation complexity was not discussed explicitly. [10] also considered existing thru functions in a scan technique but those thru functions are activated by primary inputs only.

In this paper, we introduce a new class of sequential circuits called *acyclically testable sequential circuits*, which is τ^2 -bounded. The class of acyclically testable sequential circuits that is defined in this work covers some sequential circuits that are cyclic. The variables that activate a thru function are either primary inputs or registers. In other words, the class of acyclically testable sequential circuits is a proper superset of the class of acyclic sequential circuits. We also present a design-for-test (DFT) method to augment an arbitrary sequential circuit into a circuit that belongs to the class of acyclically testable sequential circuits. We exploit the fact that RTL design information including the existence of thru functions is available early in the design cycle. For a given sequential circuit, our DFT method augments the sequential circuit with thru functions so that the sequential circuit becomes acyclically testable.

The rest of the paper is organized as follows. In Section II, we define *R-graph* as a representation of sequential circuits and introduce a new concept of testability called *acyclic testability*. Moreover, we redefine time expansion model (TEM) based on R-graph. In Section III, we discuss the test generation of acyclically testable sequential circuits. In Section IV we present the DFT method to augment an arbitrary sequential circuit into an acyclically testable sequential circuit. Experimental result is presented in Section V and the discussion is concluded in Section VI.

II. PRELIMINARIES

This section introduces a circuit representation called *R-graph* and the new concept of *acyclic testability*. We also redefine TEM based on R-graph to facilitate the discussion of test generation model in the following section.

A. R-Graph

R-graph represents the topology of circuits by grouping flip-flops (FFs) into registers and including the information about thru functions available in the logic. Thru function t is a logic that transfers the signals from the input of the thru function to the output when the thru function is active. Note that the bit width of the input and output are equal. Fig. 1 shows two examples of thru function. Two thru functions are independent if they cannot be active at the same time. t_1 and t_2 in Fig. 1(b) are independent.

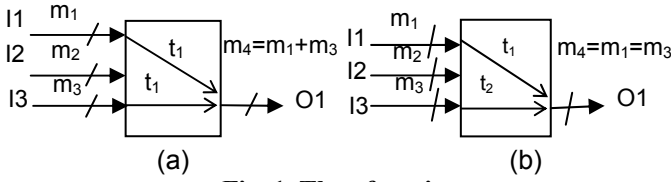


Fig. 1. Thru functions.

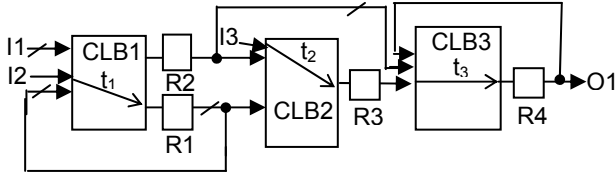


Fig. 2. Sequential circuit S1.

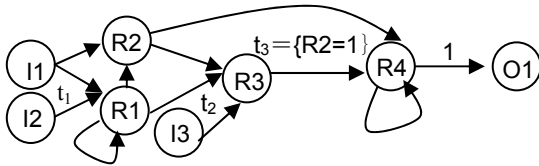


Fig. 3. R-graph of S1.

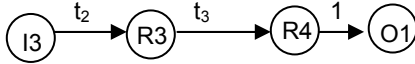


Fig. 4. A thru tree of S1.

Definition 1: A circuit representation called **R-graph** is a directed graph $G_R=(V,A,w,h,t)$ that has the following properties.

1. Let FF_i denote a flip-flop. Let $pre(FF_i)=\{FF_j \mid FF_j \xrightarrow{c} FF_i\}$ (resp. $suc(FF_i)=\{FF_j \mid FF_i \xrightarrow{c} FF_j\}$) where c is a combinational path. Vertex $v \in V$ is a register, primary input or primary output where each register consists of a maximal set of flip-flops such that $pre(FF_p)=pre(FF_q)$ and $suc(FF_p)=suc(FF_q)$ for all FF_p, FF_q in the set of flip-flops;
2. $(v_i, v_j) \in A$ denotes an arc if there exists a combinational path from the register corresponding to v_i to the register corresponding to v_j ;
3. $w:V \rightarrow Z^+$ (the set of positive integers) defines the number of flip-flops in each register corresponding to a vertex;
4. $r:V \rightarrow \{h, \phi\}$ defines the type of register where a register is a hold register if $r(v)=h$. Else, it is a regular register;
5. $t:A \rightarrow T \cup \{\phi\}$ (T is a set of thru functions $\{t_0, t_1, \dots, t_i\}$) where $t(a)=\phi$ if there is no thru function for $a \in A$ and $t(a) \neq \phi$ contains the signal values of a set of vertices that activate the thru function, in which each vertex corresponds to a register/flip-flop or PI. If $t(a)=1$ (identity thru function), the signal values are transferred from the source vertex of arc a to the sink vertex of arc a through a wire logic (not a gate logic) directly without assignment of any signal values.

The hold function of a hold register is regarded to be activated by a primary input in this work.

Example 1: Fig. 3 shows the R-graph of the sequential circuit S1 of Fig. 2. The notation CLB in Fig. 2 means combinational logic block. The thru functions t_1-t_3 , which are the thru functions extracted from the high level netlist of S1, are contained in the R-graph. $t_3=\{R2=1\}$ means thru function t_3 is activated by signal value 1 at register R2.

In the following text, the vertex that corresponds to a primary input (resp. primary output) is called input vertex (resp. output vertex) while the vertex that corresponds to a register (resp. flip-flop) is called register vertex (resp. flip-flop vertex). Note that the only incoming arc of an output vertex has identity thru function.

B. Acyclic Testability

Prior to the formal definition of the class of ayclically testable sequential circuits, the concept of thru tree is introduced.

Definition 2. Let R-graph $G_R=(V,A,w,h,t)$ represent a given sequential circuit S. A **thru tree** is a subgraph of G_R that satisfies the following conditions.

1. It is a rooted tree;
2. There is only one sink (root), which is corresponding to a primary output;
3. The sources are vertices that correspond to primary inputs;
4. All arcs are labeled with a thru function.

In the thru tree, each register is justifiable from a primary input and is observable at a primary output. Fig. 4 shows the only thru tree of the R-graph for S1. A thru function in a thru tree may depend on a signal of another thru tree to become active. Therefore, we introduce a dependency graph for a set of thru trees.

Definition 3. Let G_R be the R-graph of a sequential circuit S, and let B be a set of thru trees in G_R . The **dependency graph** of B is a directed graph $G_D=(V_D,A_D)$ such that

1. Vertex $v \in V_D$ is a thru tree in B;
2. $(v_i, v_j) \in A_D$ denotes an arc if there exists a vertex (of G_R) in thru tree v_i that activates a thru function in thru tree v_j .

Definition 4. Let R-graph $G_R=(V,A,w,h,t)$ represent a given sequential circuit S. A set of thru trees B in G_R is said to be **k-consistent** with G_R if the following conditions are satisfied.

1. The dependency graph of B is acyclic;
2. All thru trees in B are disjoint;
3. Let the maximum depth of thru trees in B be D_{max} . Let the maximum length of paths in the dependency graph of B be L_{max} . $D_{max} \times L_{max}$ is bounded by k;
4. Any vertex that activates a thru tree T_i in B is either an input vertex or a hold register vertex in B, and activates no other thru tree T_j in B;
5. For each pair of reconvergent paths p_1 and p_2 that start from u and end at v, there exists a hold register vertex w on p_1 but not on p_2 such that w is not the second vertex x of p_1 and the length of the subpath $w \rightarrow v$ of p_1 is equal to or longer than the length of any other path p_k that starts from w and ends at v if all vertices on p_1 and p_2 except u,

v and x are not included in any thru tree in B and either of the following conditions i and ii is satisfied.

- i. p_1 and p_2 are of equal length and the first arc (u,x) on p_1 is labeled with a thru function of a thru tree in B ; or
- ii. p_1 is equal to or shorter than p_2 and the vertex u activates the thru function on an arc coming to the vertex x on p_1 .

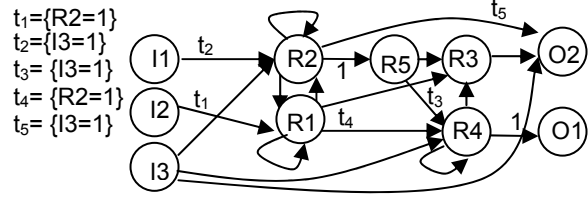
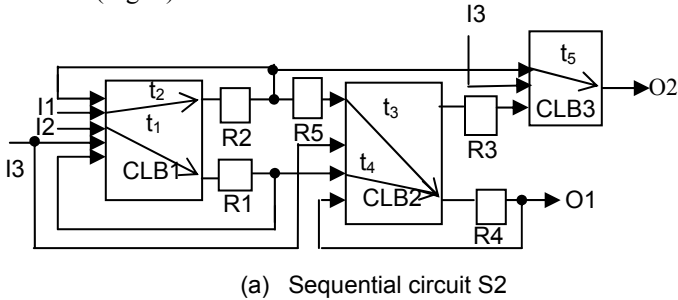
Definition 5. A sequential circuit S is said to be *k-acyclically testable* if the R-graph G_R of S contains a set of thru trees B that is *k-consistent* with G_R and covers all the vertices of a feedback vertex set of G_R . A sequential circuit S is said to be *acyclically testable* if S is *k-acyclically testable* for some constant k .

Example 2: For circuit $S1$ in Fig. 2, $R1$ and $R4$ are the vertices in the minimum feedback vertex set. However, only $R4$ is contained by the only thru tree in the R-graph as shown in Fig. 4. Therefore, $S1$ is not acyclically testable.

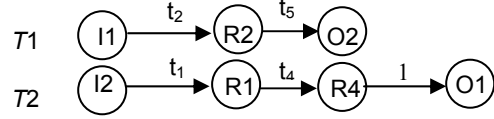
Example 3: Fig. 5(b) shows an R-graph of a sequential circuit called $S2$ (Fig. 5(a)) whose registers are hold registers. Thru functions $t_1=\{R2=1\}$ and $t_4=\{R2=1\}$ are activated by $R2$ and thru functions $t_2=\{I3=1\}$, $t_3=\{I3=1\}$ and $t_5=\{I3=1\}$ are activated by $I3$. $S2$ is an acyclically testable circuit because there are two thru trees, namely $T1$ and $T2$ (shown in Fig. 5(c)) that contain $R1$, $R2$ and $R4$, which are the vertices in the minimum feedback vertex set. Although $T3$ contains all the vertices in the minimum feedback vertex set, the thru tree does not satisfy Condition 1 in Definition 4. Thru functions t_1 and t_4 are activated by $R2$, which is also in the same thru tree. In other words, the dependency graph of $T3$ is cyclic.

An acyclic sequential circuit is an acyclically testable sequential circuit with empty minimum feedback vertex set. In other words, a sequential circuit is acyclically testable if it is acyclic but the converse is not correct. Therefore, we have the following theorem.

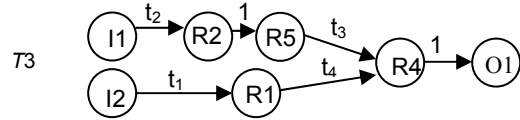
Theorem 1. The class of acyclically testable sequential circuits is a proper superset of the class of acyclic sequential circuits (Fig. 6).



(b) R-graph of $S2$



(c) Thru trees $T1$ and $T2$



(d) Thru tree $T3$

Fig. 5. $S2$, its R-graph and thru trees.

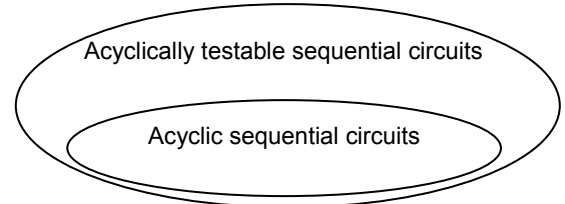


Fig. 6. Acyclically testable sequential circuits and acyclic sequential circuits.

C. Time Expansion Model

Time expansion model (TEM) has been introduced in [7], [8] as a test generation model for acyclic sequential circuits based on time expansion graph (TEG). A topology graph is a directed graph of circuit representation where a vertex v denotes a combinational logic block while an arc (u,v) represents a connection from combinational logic block u to combinational logic block v . The authors defined time expansion graph (TEG) for the topology graph of a given acyclic sequential circuit. To facilitate the discussion of test generation model for acyclically testable sequential circuits, we redefine the time expansion graph (TEG) that is used to derive a time expansion model for a given acyclic sequential circuit represented by R-graph.

Definition 6. Let S be an acyclic sequential circuit and let $G_R=(V,A,w,h,t)$ be the R-graph of S . Let $G_T=(V_E,A_E,T,l)$ be a directed graph, where V_E is a set of vertices, A_E is a set of arcs, T is a mapping from V_E to a set of integer and l is a mapping from V_E to the set of vertices in R . If graph G_T satisfies the following five conditions, graph G_T is said to be a *time-expansion graph (TEG)* of G_R .

C1 (Input/Output and register preservation): The mapping l is a surjective, i.e., $\forall v \in V, \exists u \in V_E, \text{ s.t. } v=l(u)$.

C2 (Logic preservation): Let u be a vertex in G_R . For any direct predecessor $v(\in \text{pre}(u))$ of u in G_R , there exists vertices x and w in G_T such that $l(w)=u$, $l(x)=v$, $x \in \text{pre}(w)$ and $|\text{pre}(w)|=|\text{pre}(u)|$.

C3 (Time consistency): For any arc $(u,v) (\in A_E)$, there exists an arc $(l(u),l(v))$ such that $T(v)-T(u)=1$ if $l(u)$ corresponds to a register or a primary input and $l(v)$ corresponds to a register. $T(v)-T(u)=0$ if $l(u)$ corresponds to a register and $l(v)$ corresponds to a primary output.

C4 (Time uniqueness): For any pair of vertices $u,v (\in V_E)$, if $T(u)=T(v)$ and if $l(u)=l(v)$, then the vertices u and v are identical, i.e., $u=v$.

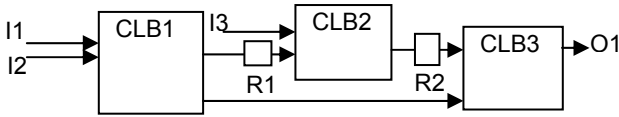
C5 (Hold consistency): Let u be a vertex in G_T . Let $v(\in \text{pre}(u))$ be a direct predecessor of u . If $|\text{pre}(u)| < |\text{pre}(l(u))|$ and $l(u)=l(v)=w$, then $r(w)=h$ and $|\text{pre}(u)|=1$.

Definition 7. Let S be an acyclic sequential circuit. Let $G_R=(V,A,w,h,t)$ be the R-graph of S , and let $G_T=(V_E,A_E,T,l)$ be a TEG of G_R . The combinational equivalent $C_E(S)$ obtained by the following procedure is said to be **the time expansion model (TEM) of S based on G_T** .

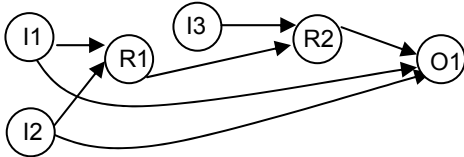
1. For each time frame, replace each vertex with a connection without a register and replace each arc with the combinational logic block where the corresponding combinational path (represented by the arc) is located. Each combinational logic block appears at most once at each time frame.

2. A logic gate in each logic block is removed if it is not reachable to any input of other logic blocks.

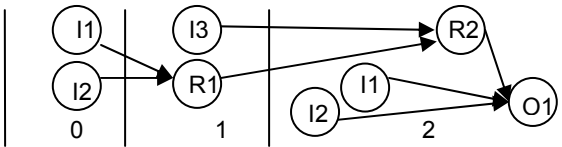
Example 4: Fig. 7(b) shows the R-graph of one of the acyclic sequential circuit S_3 in Fig. 7(a). Its time expansion graph (TEG) and its time expansion model (TEM) are derived in Fig. 7(c) and Fig. 7(d).



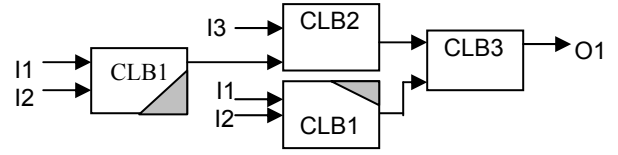
(a) Acyclic sequential circuit, S_3 .



(b) R-graph of an acyclic structure of S_3 .



(c) Time expansion graph of S_3 .



(d) Time expansion model (TEM) of S_3 .

Fig. 7. Example of time expansion model.

III. TEST GENERATION MODEL AND PROCEDURE

This section introduces the test generation model called acyclically-extended time expansion model (ATEM) to perform test generation on acyclically testable sequential circuits. The procedure of test generation is also described.

A. Acyclically-Extended Time Expansion Model (ATEM)

An *acyclically-extended time expansion model (ATEM)* of an acyclically testable circuit is created using its R-graph and its thru trees. We define *acyclically-extended time expansion graph (ATEG)* and then ATEM. In the following text, $\text{pre}(u)$ denotes the set of direct predecessors of u while $|\text{pre}(u)|$ denotes the number of all direct predecessors of u .

Definition 8. Let S be an acyclically testable sequential circuit with thru trees B and let $G_R=(V,A,w,h,t)$ be the R-graph of S . The *acyclically-extended time expansion graph (ATEG)* $G_A=(V_A,A_A,T,l)$ with respect to B is a directed graph that satisfies the following conditions.

C1 (Input/Output and register preservation): The mapping l is a surjective, i.e., $\forall v \in V, \exists u \in V_A, \text{ s.t. } v=l(u)$.

C2 (Logic preservation for fault excitation): Let u be a vertex in G_R . For any direct predecessor $v(\in \text{pre}(u))$ of u in G_R , there exists vertices x and w in G_A such that $l(w)=u$, $l(x)=v$, $x \in \text{pre}(w)$ and $|\text{pre}(w)|=|\text{pre}(u)|$.

C3 (Thru tree for justification and propagation): Let u be a vertex in a thru tree $T_i \in B$. Let $W \subset \text{pre}(u)$ be a set of all direct predecessors of u in T_i . For each $u \in T_i$, there exists a vertex v in G_A which satisfies the following conditions.

- i. $l(v)=u$;
- ii. For each vertex $x \in \text{pre}(v)$, the following conditions are satisfied.
 - a. If there exists a vertex w' in W such that $l(x)=w'$ then $x \notin \text{pre}(z)$ for any z where $l(z)$ is a vertex included in other thru trees except T_i and $x \notin \text{pre}(y)$ for $l(y)=l(x)$;
 - b. Let T_k be a thru tree that is activated by $l(x)$. If $l(x)=l(v)$, then $|\text{pre}(v)|=1$ and $x \notin \text{pre}(z)$ for any z where $l(z) \neq l(v)$ and $l(z)$ is a vertex not in thru tree T_k ;
 - c. If $l(x)$ is a vertex that activates T_i , then $x \notin \text{pre}(z)$ for any z where $l(z) \neq l(x)$ and $l(z)$ is a vertex not in thru tree T_i .

C4 (Time consistency): For any arc $(u,v) (\in A_A)$, there exists an arc $(l(u),l(v))$ such that $T(v)-T(u)=1$ if $l(u)$ corresponds to a register or a primary input and $l(v)$ corresponds to a register. $T(v)-T(u)=0$ if $l(u)$ corresponds to a register and $l(v)$ corresponds to a primary output.

C5 (Time uniqueness): For any pair of vertices $u, v (\in V_A)$, if $T(u)=T(v)$ and if $l(u)=l(v)$, then the vertices u and v are identical, i.e., $u=v$.

C6 (Hold consistency): Let u be a vertex in G_A . Let $v(\in \text{pre}(u))$ be a direct predecessor of u . If $|\text{pre}(u)| < |\text{pre}(l(u))|$ and $l(u)=l(v)=w$, then $r(w)=h$ and $|\text{pre}(u)|=1$.

C7 (Input Independency): Let u, v be two vertices in G_A . Let p_i and p_j be a pair of reconvergent paths that start from u and end at v . Let w be a vertex on p_i such that $u \in \text{pre}(w)$. Let x be a vertex on p_j such that $u \in \text{pre}(x)$. For each pair of paths p_i, p_j where $w \neq x$, $|\text{pre}(w)|=|\text{pre}(l(w))|$ and $|\text{pre}(x)|=|\text{pre}(l(x))|$.

Definition 9. Let S be an acyclically testable sequential circuit. The *acyclically-extended time expansion model (ATEM)* of S is the combinational equivalent obtained by the following procedure.

1. For each time frame, replace each vertex with a connection without a register and replace each arc with the combinational logic block where the corresponding combinational path (represented by the arc) is located. Each combinational logic block appears at most once at each time frame.
2. A logic gate in each logic block is removed if it is not reachable to any input of other logic blocks.
3. Each input that corresponds to an output of a register is assigned don't care value.

Example 5: For simplicity, Fig. 8 shows the ATEG and ATEM for the subcircuit of S_2 which is fan-in cone with output O_2 . ATEG and ATEM for the whole circuit can be derived similarly. Note that T_2 is dependent on T_1 . Justification of registers R_1, R_2 and R_4 at time 3 is done from time 0 to 3. Note that when R_2 of T_1 is justified through I_1 from time 2 to 3, R_1 and R_4 of T_2 are in hold mode at time 4 (required by c of ii of C_3 in Definition 8). R_2 of T_1 needs to be assigned certain signal value to activate thru functions t_1 and t_4 but R_2 cannot be used for justification and activation simultaneously.

B. Test Generation Procedure

For each stuck-at fault, the test generation process is done as follows using ATEM test generation algorithm. The fault list include faults in thru functions. To guarantee the test generation for faults in thru functions, each register in the feedback vertex set are regarded as having reset function.

Step 1: Generate ATEM of the sequential circuit.

Step 2: Apply combinational ATPG for multiple fault model to the ATEM.

Step 3: Derive the test sequence from the test pattern obtained for the ATEM.

Lemma 1: The ATEM of an acyclically testable sequential circuit is sufficient to generate tests for all testable faults in the circuit.

From Lemma 1, the following theorem is concluded.

Theorem 2: The ATEM test generation algorithm can identify redundancy and all testable faults.

Theorem 3: The test generation complexity of the acyclically testable sequential circuits is τ^2 -bounded.

Proof: From the definition of ATEM, the number of time frames in the ATEM can extend at most $dk + k + d$, where k is at most the total depth of all the thru trees and d is the depth of the acyclic structure of the acyclically testable circuit. By assuming $d=O(n)$, the size of ATEM is $(k+1)O(n^2)+kO(n)$ where n is the size of the acyclically testable circuit. Since the test generation is done by applying combinational ATPG on ATEM, the test generation complexity is $O(\tau^2(n))$.

IV. DFT METHOD

In this section, a DFT method to augment a given sequential circuit into an acyclically testable sequential circuit is introduced. The DFT method performs some operations on R-graph and it is designed to induce minimum area overhead. The procedure consists of the following three steps.

Step 1: Identify the vertices of minimum feedback vertex set (MFVS).

Step 2: Group the vertices of MFVS into two groups, G_1 and G_2 . One group contains input/output vertices and the vertices that activate a thru function. Another group contains input/output vertices and register vertices that are not in G_1 . The set of vertices in G_1 is disjoint with G_2 .

Step 3: For each group, build a thru tree by adding minimum new thru functions. Each register is added a reset function if it does not have one.

Step 4: If G_1 and G_2 have registers, hold function is added to each register. Else, hold function is added to each register that is in neither G_1 nor G_2 . The control input for hold registers in G_1 is different from the control input for hold registers in G_2 .

Example 6: S_1 in Fig. 2 is not acyclically testable because R_1 and R_2 are not contained by any thru tree. By adding new thru functions to arcs (R_1, R_3) and (R_3, R_4) that are activated by a new input I_4 , it becomes acyclically testable. Both R_1 and R_4 are justifiable from I_2 and observable at O_1 .

V. CASE STUDIES

In the case studies, we conduct experiments on RTL benchmark circuits, which are datapaths of varying bit width. We apply our DFT method on GCD_dp, LWF_dp, JWF_dp, and MPEG_dp and compare the area overhead of the augmented circuits with that of the full scanned circuits and the partial scanned circuits. Partial scanned circuits are the circuits whose minimum feedback set of flip-flops are scanned so that the augmented circuits are acyclic. Thus, the circuits modified with partial scan and with our DFT method have same test generation complexity. Table 1 presents the characteristics of the benchmark circuit. Table 2 shows the fault coverage and fault efficiency of each benchmark circuit. Each fault testable in the partial scan designed circuits is also testable in the corresponding circuit augmented by our DFT method, and vice versa. Table 3 shows the area overhead where one unit of area corresponds to the size of an inverter and pin overhead. It shows that the area overhead of the

benchmark circuits augmented by our method is less than that of the full scanned circuits and the partial scanned circuits. The pin overhead in our method comes from the reset function and extra input to control the new thru functions. Table 4 tells that the test generation time for the original circuits is large while the test generation time for the partial scan designed circuits as well as the acyclically testable sequential circuits is small. Table 5 gives the information that the test application time of the circuits under our augmentation is more than the original circuits' but less than the partial scan.

VI. CONCLUSION

A new class called acyclically testable sequential circuits has been introduced. The test generation complexity of the acyclically testable sequential circuits is τ^2 -bounded. On the other hand, acyclically testable sequential circuits are at-speed testable. The DFT method to augment an arbitrary sequential circuit into an acyclically testable sequential circuit has been introduced. Experimental results showed that the area overhead of the resulting augmented circuits is less compared to the partial scan designed circuits. Complete fault efficiency is also achieved and the test generation time is low. Moreover, the test application time is less than the test application time of the full scanned circuits and partial scanned circuits.

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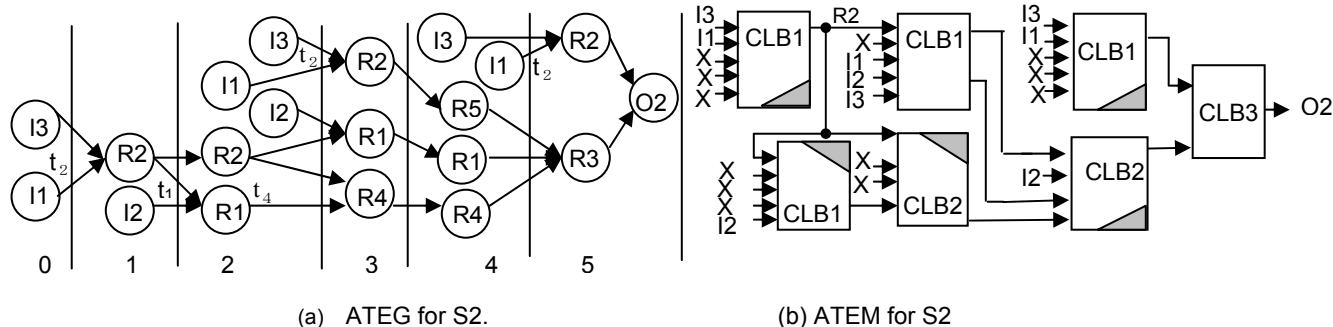


Fig. 8. Test generation model for acyclically testable sequential circuits.

TABLE 1. CHARACTERISTICS

RTL benchmark	Original			
	FF	Area	PI	PO
GCD_dp	48	1383	40	19
LWF_dp	80	1763	39	32
JWF_dp	224	5925	106	80
MPEG_dp	1928	46772	499	128

TABLE 2. FAULT EFFICIENCY AND FAULT COVERAGE

RTL benchmark	Original		Full Scan		Partial scan		Our method	
	FC(%)	FE(%)	FC(%)	FE(%)	FC(%)	FE(%)	FC(%)	FE(%)
GCD_dp	99.75	99.75	100	100	100	100	100	100
LWF_dp	99.94	99.94	100	100	100	100	100	100
JWF_dp	98.70	98.70	100	100	100	100	100	100
MPEG_dp	84.80	84.80	100	100	100	100	100	100

TABLE 3. AREA AND PIN OVERHEAD

RTL benchmark	Full scan		Partial scan		Our method	
	Area (OH%)	Pin OH	Area (OH%)	Pin OH	Area(OH%)	Pin OH
GCD_dp	1719(24.30)	3	1495(8.10)	3	1415(2.31)	1
LWF_dp	2323(31.76)	3	1875(6.36)	3	1798(1.99)	2
JWF_dp	7493(26.46)	3	6485(9.45)	3	5957(0.54)	2
MPEG_dp	60268(28.85)	3	47612(1.80)	4	47556(1.68)	2

TABLE 4. TEST GENERATION TIME AND TEST APPLICATION TIME

RTL benchmark	Test Generation Time (s)				Test Application Time (Clock Cycles)			
	Original	Full scan	Partial scan	Our method	Original	Full scan	Partial scan	Our method
GCD_dp	87.19	0.02	0.19	0.43	159	5830	3603	1304
LWF_dp	49.02	0.02	0.06	0.40	59	3725	1931	475
JWF_dp	1689.14	0.08	0.50	13.48	103	16874	11786	1885
MPEG_dp	2646.42	0.18	12.05	33.91	114	154320	305829	46238